

Semi-Supervised Learning for Automatic Improvement of Onboard Object Detection Models on Small Satellites

Lucas Tsutsui da Silva¹ (l.tsutsui_da_silva@unsw.edu.au), Gustavo Batista¹, Tat-Jun Chin², Yang Song¹, and Will Heyne³

Introduction

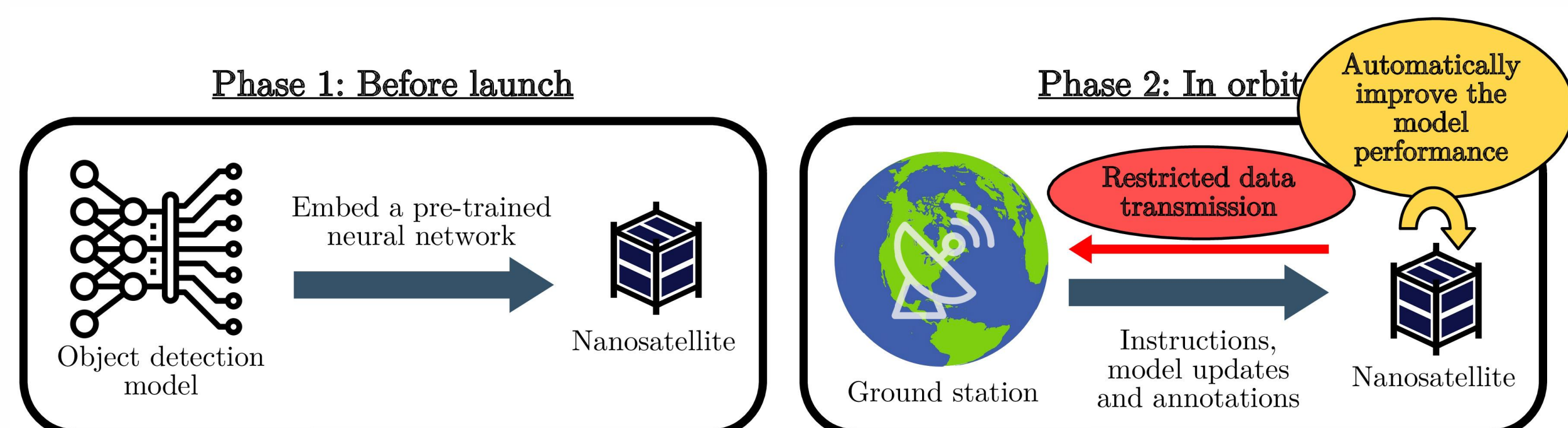
- Nanosatellites and CubeSats offer a short development time and low production costs for Earth observation missions at the cost of having restricted power, size, and communication bandwidth
- Despite the limitations, it is possible to employ small edge computing platforms (e.g., NVIDIA Jetson, Intel Movidius Myriad, and Google Coral) and neural network simplification strategies (SZE et al., 2017) to perform onboard image processing on nanosatellites and CubeSats
- An onboard ML model can process images captured by a satellite to select a few images of interest to be transmitted to the ground, reducing bandwidth usage and power consumption
- Current approaches of onboard image processing implement image classification for cloud detection (GIUFFRIDA et al., 2020) and image segmentation for flood mapping (MATEO-GARCIA et al., 2021)
- They have some limitations, such as using a static ML model, ignoring images not selected for downlinking, and potentially causing sample bias

Challenges

- Efficient training: performing onboard SSOD training is challenging due to the severe restrictions on the nanosatellite hardware
- Robust detection of small objects and minority categories: objects of interest are small and infrequent in images captured by nanosatellites
- Domain adaptation: access to labeled images of the target domain is limited and hinders adapting a pre-trained model

Objectives

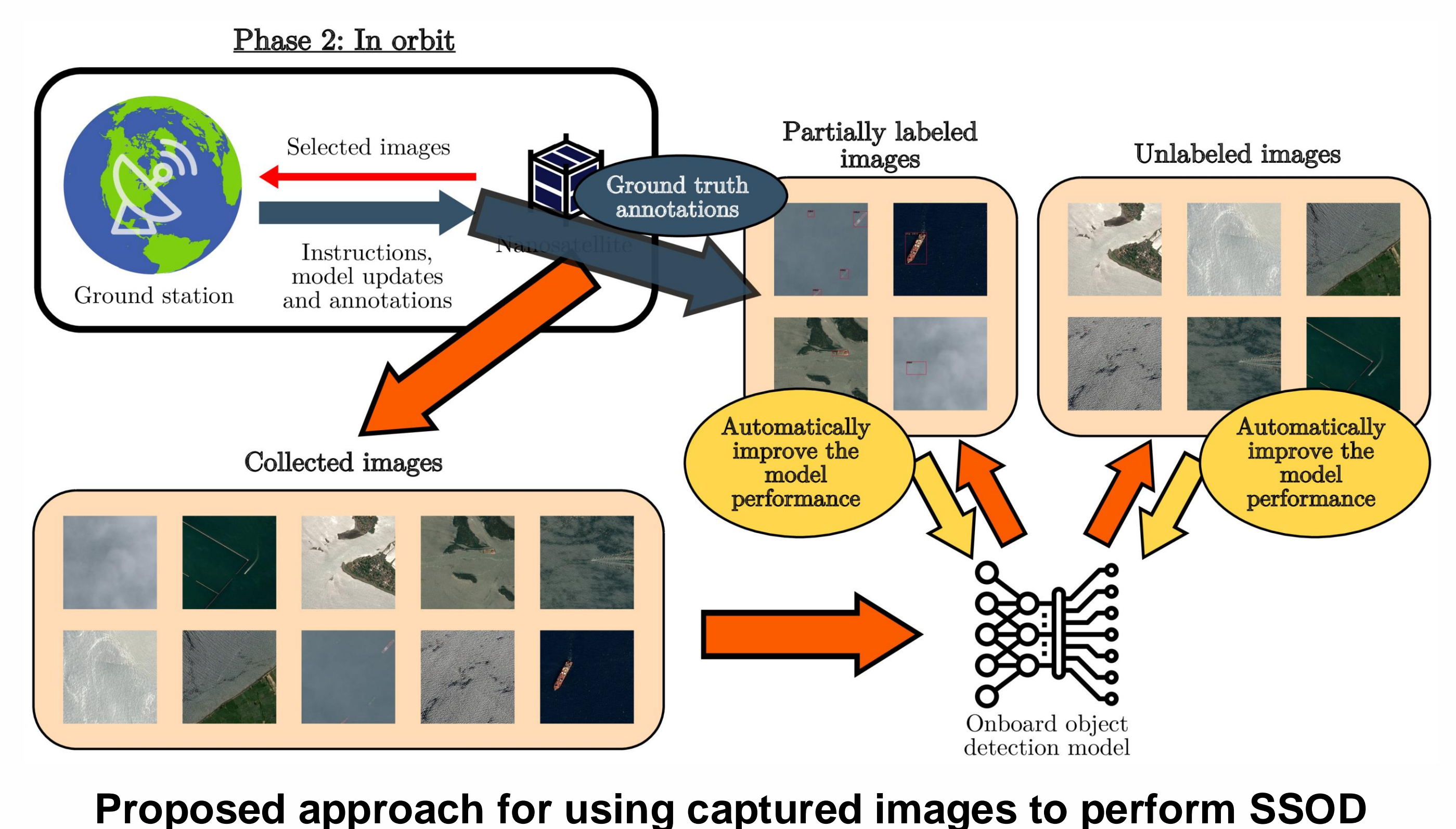
- Develop SSOD methods that address the specific challenges of nanosatellite applications
- Demonstrate the effectiveness of our SSOD solutions with satellite imagery datasets and execute them on a CubeSat testbed



The pipeline for self-improvement of object detection models in orbit.

Methods

- Supervised learning is not a viable solution to improve the performance of an onboard model, since it requires using only labeled images, and labeling involves transmitting images to the ground and manually labeling them
- This research proposes to use the images captured by the satellite to automatically improve the performance of the onboard ML model
- We focus on object detection task and assume that a few labeled images can be acquired via active learning; the remaining images are unlabeled
- Therefore, we can apply semi-supervised object detection (SSOD) to use labeled and unlabeled images in order to improve the detection performance of the onboard model



Proposed approach for using captured images to perform SSOD

References

- GIUFFRIDA, G. et al., "Cloudscout: A deep neural network for on-board cloud detection on hyperspectral images". Remote Sensing, MDPI, v. 12, n. 14, p. 2205, 2020.
- MATEO-GARCIA, G. et al., "Towards global flood mapping onboard low cost satellites with machine learning". Scientific reports, Nature Publishing Group UK London, v. 11, n. 1, p. 7249, 2021.
- SZE, V. et al., "Efficient processing of deep neural networks: A tutorial and survey". Proceedings of the IEEE, IEEE, v. 105, n. 12, p. 2295–2329, 2017.

¹University of New South Wales Sydney, ²The University of Adelaide, ³BAE Systems Australia